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# **GSM PROTOCOL STACK**

## **G23**

### **BZ – BUZZER DRIVER**

### **DRIVER INTERFACE**

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- [ISO 9000:2000] International Organization for Standardization. Quality management systems - Fundamentals and vocabulary. December 2000

## 1 Introduction

G23 is a software package implementing Layers 2 and 3 of the ETSI-defined GSM air interface signaling protocol, and as such represents the part of a GSM mobile station's protocol software which is both, platform and manufacturer independent. Therefore, G23 can be viewed as a building block providing standardized functionality through generic interfaces for easy integration.

The G23 suite of products consists of the following items:

- Layers 2 and 3 for speech & short message services,
- Layers 2 and 3 for fax & data services,
- Application Control Interface, AT Command Interface
- MMI and MMI Framework (MFW)
- Test and integration support tools.

This document describes the functional interface of the G23 Buzzer driver. This driver is used to play single tones or melodies by the buzzer and to control the buzzers functions. The addresses and masks for the Buzzers control registers are hardware depending and must be set for each integration. Melodies are played by use of timers and control structures for the buzzer tones. Melodies are files with records of tone descriptions. If plugging /unplugging of a buzzer could be detected, those events have to be signaled to the upper layers via the callback function.

## 2 Interface description of the Buzzer driver

### 2.1 Data types

Name	Description
T_DESCR	Buzzer tone description
T_ACT_TONE	actual output tone description
T_BZ_CB_FUNC	call-back function type
UBYTE	unsigned 8 bit integer data type
BYTE	signed 8 bit integer data type
USHORT	unsigned 16 bit integer data type
SHORT	signed 16 bit integer data type

#### 2.1.1 T\_BZ\_CB\_FUNC

**Definition:**

```
typedef void (*T_BZ_CB_FUNC) (T_DRV_SIGNAL* in_SignalIDPtr) ;
```

**Description:**

This type defines a call-back function. This function is called when a device has stopped playing a sound or melody. For more details refer to the description of the status call-back function in the chapter describing the exported functions.

## 2.1.2 T\_DESCR Type – Buzzer Tone Description

**Definition:**

```
typedef struct
{
    USHORT    frequency;
    UBYTE     volume;
    USHORT    length;
} T_DESCR;
```

**Description:**

This data type represents the characteristics frequency, volume and duration of a single buzzer tone.

Data element	Description
Frequency	Frequency of the tone in Hz.
Volume	Volume of buzzer during playing this tone (0= min, 0xFF = max).
Length	Length of the tone in milliseconds (0: endless)

## 2.1.3 T\_ACT\_TONE Type – Description of current buzzer status

**Definition:**

```
typedef struct
{
    UBYTE     status;
    UBYTE     call_tone;
    UBYTE     type;
    T_DESCR   * descr;
    int       FileSize;
    UBYTE     volume;
    UBYTE     style;
    USHORT    descr_index;
} T_ACT_TONE;
```

**Description:**

This data type represents the current characteristics of the buzzer.

Data element	Description
Status	BUZZER_SILENT, NO_TONE, BUZZER_ON, TONE_SILENT
Call_tone	Index of tone in tone table (for the use of a tone generator)
Type	BUZZER or AUDIO : play tone over buzzer or speaker?
Descr	Actual tone description
FileSize	Size of the description file in multiples of T_DESCR
Volume	Actual buzzer volume
Style	Repeats of played file
Descr_index	Actual record number in tone description file

## 2.2 Constants

Name	Description
BZ_CNTL0	Buzzer control register 0
BZ_CNTL1	Buzzer control register 1
BZ_CNTL2	Buzzer control register 2
BZ_CNTL3	Buzzer control register 3
BZ_LEVEL	Buzzer level control register
BZ_ON	Buzzer on/off bit in control register
BZ_NOTCONFIGURED	Device is not configured
BZ_BUSY	Device or driver is busy or already in use
BZ_FOREVER	The melody/sound shall be played until manually stopped
BZ_SIGTYPE_SOUNDEND	Indicating the device has stopped playing a sound
DRV_BUFFER_FULL	The internal buffer is exhausted
DRV_DISABLED	Driver is not enabled
DRV_ENABLED	Driver is enabled
DRV_NOTCONFIGURED	Driver is not configured
DRV_INITFAILURE	Driver initialization failed
DRV_INITIALIZED	Driver is already initialized
DRV_INTERNAL_ERROR	Unspecified internal driver error
DRV_INPROCESS	The requested function is currently being executed
DRV_INVALID_PARAMS	One or more parameters are out of range or invalid
DRV_NOTCONFIGURED	Driver is not configured
DRV_OK	Return value indicating the function completed successfully
DRV_UNKNOWN	unknown device accessed

## 2.3 Functions

Name	Description
BZ_Init	Initialization of the driver
BZ_Exit	Termination of the driver
BZ_Enable	activate the buzzer
BZ_Disable	stops the buzzer
BZ_PlayStruct	play a single tone
BZ_Volume	set the buzzer volume
BZ_KeyBeep	Audio feedback to user after keypress
BZ_PlayFile	Start playing a melody/sound
BZ_Abort	Abort/stop playing the current melody/sound
BZ_SetCallBack	Define a call-back called when the end status is reached
BZ_CheckHW	Check, whether a buzzer is connected or not

### 2.3.1 BZ\_Init – Driver Initialization

**Definition:**

```
USHORT BZ_Init(
    USHORT          DrvHandle
    T_BZ_CB_FUNC    in_StatusCallbackPtr
    T_DRV_EXPORT ** DrvInfo
);
```

**Parameters:**

Name	Description
DrvHandle	unique handle for this driver
in_StatusCallbackPtr	pointer to callback function
DrvInfo	pointer to the driver parameters (see GDI specification document for a description of T_DRV_EXPORT).

**Return values:**

Name	Description
DRV_OK	Initialization successful
DRV_INITIALIZED	Driver already initialized

**Description**

The function initializes the driver's internal data.

The driver exports its properties like its name, the functions to access driver functionality and a bitfield called flags by the parameter DrvInfo. If the driver is called by ISR, Bit(0) in the bitfield is set, otherwise this bit is cleared.

The driver stores the DrvHandle and passes it over the SignalID to the calling process every time the callback function is called.

### 2.3.2 BZ\_Exit - Termination of the driver

**Definition:**

```
void BZ_Exit(void)
```

**Parameters:**

Name	Description
-	

**Return values:**

Name	Description
-	

**Description**

The function is called when the driver functionality is no longer needed. The function de-allocates the resources.

### 2.3.3 BZ\_Enable – activate the buzzer

**Definition:**

```
USHORT BZ_Enable(void) ;
```

**Parameters:**

Name	Description
-	

**Return values:**

Name	Description
DRV_OK	Function successful
BZ_BUSY	The device is already open

**Description**

The function activates the buzzer. The buzzer is now ready to play tones.

## 2.3.4 BZ\_Disable – stops the buzzer

### Definition:

```
USHORT BZ_Disable(void);
```

### Parameters:

Name	Description
Caller	handle of calling process

### Return values:

Name	Description
DRV_OK	Function successful
DRV_ACCESS_DENIED	The device is opened by another process

### Description

The function stops the buzzer. The buzzer stops playing melodies or tones immediately. Any further calls of BZ\_Tone() will have no effect until BZ\_Enable() is called.

## 2.3.5 BZ\_PlayStruct – play a single tone

### Definition:

```
void BZ_PlayStruct(  
    T_DESCR      tone);
```

### Parameters:

Name	Description
tone	tone description

### Return values:

Name	Description
-	-

### Description

The function starts playing a tone with the settings in the tone description.

## 2.3.6 BZ\_Volume – set the buzzer volume

### Definition:

USHORT BZ\_Volume( UBYTE v);

### Parameters:

Name	Description
v	Buzzer volume (0=min, 0xFF = max).

### Return values:

Name	Description
DRV_OK	Configuration successful
DRV_INVALID_PARAMS	One or more parameters are out of range or not allowed in that combination

### Description

The function sets the Buzzer volume immediately.

## 2.3.7 BZ\_KeyBeep – Audio feedback to user after keypress

### Definition:

```
void BZ_KeyBeep(void);
```

### Parameters:

Name	Description
-	-

### Return values:

Name	Description
-	-

### Description

The function produces a tone over the buzzer to give the user a feedback after a keypress. The tone can be equal for every key or a unique tone (perhaps DTMF) for each key.

## 2.3.8 BZ\_Playfile – Play a sound or melody

### Definition:

```
USHORT BZ_Playfile  
(  
    T_ACT_TONE      in_Sound  
    int             in_Repeats  
);
```

### Parameters:

Name	Description
in_Sound	Description of buzzer parameters for paying the sound / melody.
in_Repeats	Identifies the number of repetitions of the sound.

### Return values:

Name	Description
DRV_OK	Sound is started successfully
DRV_INVALID_PARAMS	One or more parameters are out of range or not valid

### Description

This function is used to play a sound. If the device is currently playing a sound, this sound will be stopped and instead the new sound will be played. The function returns immediately after the “play process” has been activated. If the calling process should be notified when the sound has stopped playing automatically, the process has to set a call-back function or a signal using the BZ\_SetCallback function.

### 2.3.9 BZ\_AbortSound – Abort playing a sound or melody

**Definition:**

```
USHORT BZ_AbortSound  
(  
void  
);
```

**Parameters:**

Name	Description
-	

**Return values:**

Name	Description
DRV_OK	Sound is stopped successfully
DRV_ACCESS_DENIED	Sound could not be stopped

**Description**

This function is used to manually abort playing a sound. When calling this function whether the call-back will be called nor a signal will be set indicating that the device has stopped playing a sound.

### 2.3.10 BZ\_SetCallback – Set a call-back function

**Definition:**

```
USHORT BZ_SetCallback  
(  
    T_BZ_CB_FUNC    in_StatusCallbackPtr,  
);
```

**Parameters:**

Name	Description
in_StatusCallbackPtr	This parameter points to the function that is called when the status of a device has changed. This parameter can be NULL if you don't wish to be informed about status changes.

**Return values:**

Name	Description
DRV_OK	Function completed successful
DRV_ACCESS_DENIED	Driver is in use by another process

**Description**

This function is used to set call-back function the driver calls when the status of the a specific device has changed. This function can be called at any time after initialization. To remove a call-back call this function setting the parameter for the corresponding call-back to NULL.

### 2.3.11 BZ\_CheckHW - Check, whether a buzzer is connected or not

**Definition:**

```
USHORT BZ_CheckHW  
(  
    USHORT          DeviceID);
```

**Parameters:**

Name	Description
DeviceID	Device to check (if multiple devices supported), ID's set by driver.

**Return values:**

Name	Description
TRUE	device detected
FALSE	device not found

**Description**

This function checks the presence of the specified (buzzer) device.

## Appendices

### A. Acronyms

**DS-WCDMA** Direct Sequence/Spread Wideband Code Division Multiple Access

### B. Glossary

**International Mobile Telecommunication 2000 (IMT-2000/ITU-2000)** Formerly referred to as FPLMTS (Future Public Land-Mobile Telephone System), this is the ITU's specification/family of standards for 3G. This initiative provides a global infrastructure through both satellite and terrestrial systems, for fixed and mobile phone users. The family of standards is a framework comprising a mix/blend of systems providing global roaming. <URL: <http://www.imt-2000.org/>>